

# CSE 505 Final Examination

Date: Wednesday, January 5<sup>th</sup>, 2005

Duration: One Week

## • Problem 1

A factory has a conveyor belt, on which wooden planks of different sizes travel with no gaps in between. The lengths of the planks are exponentially distributed, with parameter  $\lambda$ . (In other words, if we denote the length of a single plank with the random variable  $x$ ,  $f_x(x_0) = \lambda e^{-\lambda x_0}$ .)

Given this information, the average length of the planks is  $1/\lambda$ .

Here is an interesting apparent paradox: Since the lengths are exponentially distributed, the arrivals of the endpoints (separation points) is a Poisson process. Suppose while the planks are passing, we stop the belt at a random time, say, by driving a knife into the plank currently in front of us. Now, the expectation value of the length until the end of the plank (from our knife) is  $1/\lambda$ . Now, if we consider the distance *since* the beginning of the plank to our knife, the expectation value of that is also  $1/\lambda$ . Therefore, the expectation value of the total length of the plank, which is the sum of these two lengths, is  $2/\lambda$ !

The question is this: The average length of the planks is  $1/\lambda$ , but when we catch one, we see the average length is  $2/\lambda$ ! How does this happen? Which one is right? Or what is happening? Only explanations hitting the problem on the head will receive points.

## • Problem 2

The state transition matrix for a discrete-state, discrete transition Markov process with two states is given as:

$$A = \begin{bmatrix} a & b \\ 1-a & 1-b \end{bmatrix}$$

In this notation, the state probability vector is denoted as a column vector (which is different than what we have in the book). Note that this is the most general case for a two-state system.

Since this  $A$  is the one-step transition matrix, the two, three,  $n$ -step transition matrices are  $A^2$ ,  $A^3$ ,  $A^n$ .

The most general state probability vector is:

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

where  $x_1 + x_2 = 1$ .

a. Calculate the two- and three- step state transition matrices.

b. By any means you can, calculate the elements of the matrix  $A^n$  as a function of  $n$ , for all  $n > 0$ .

c. Define  $\vec{x}_n = A^n \vec{x}$ . Calculate  $\vec{x}_\infty = \lim_{n \rightarrow \infty} \vec{x}_n$ , which is the limiting state probability vector.

d. Under what conditions does  $\vec{x}_\infty$  become independent of  $\vec{x}$ , the initial state probability vector?

e. How fast does  $\vec{x}_n$  converge to  $\vec{x}_\infty$ ? In other words, what is the dependence of convergence on the parameters  $a$  and  $b$ ?

## • Problem 3

a. A discrete-state discrete-transition Markov process has three states. The state transition probabilities at each step from state  $i$  to state  $j$  are given by the state transition matrix  $p_{ij}$ . It is known that  $p_{ij} = p_{ji} > 0$  for all pairs  $(i, j)$ . Find the limiting state probabilities  $P_i$  in terms of  $p_{ij}$ .

**b.** This time, consider a Markov process with  $N$  states, with the same property that  $p_{ij} = p_{ji} > 0$ . Find the limiting state probabilities  $P_i$  in terms of  $p_{ij}$ . (The result is very important for quantum statistical mechanics.)